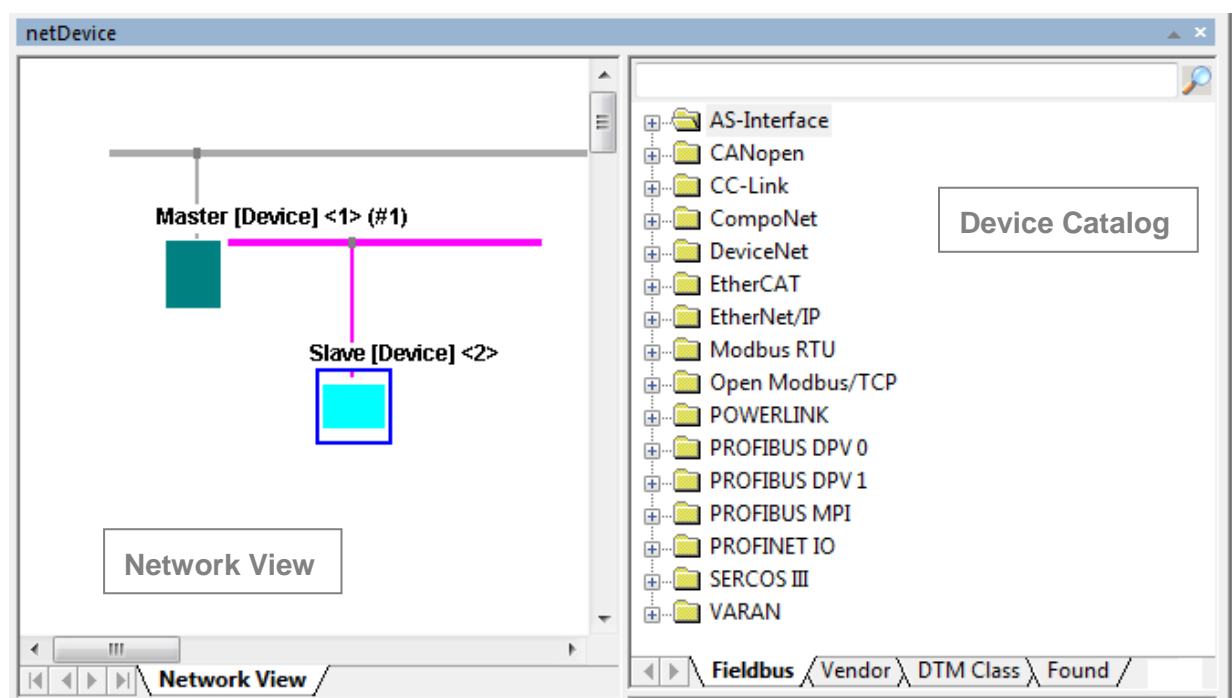


**Operating Instruction Manual**  
**netDevice and netProject**  
**FDT Container**



**Hilscher Gesellschaft für Systemautomation mbH**

**[www.hilscher.com](http://www.hilscher.com)**

DOC040401OI14EN | Revision 14 | English | 2017-03 | Released | Public

# Table of Contents

1	INTRODUCTION.....	4
1.1	About this Manual .....	4
1.1.1	Overview.....	4
1.1.2	Online Help.....	4
1.1.3	List of Revisions .....	5
1.1.4	Conventions in this Manual .....	5
1.2	Legal Notes.....	6
1.3	Registered Trademarks.....	9
2	SAFETY .....	10
2.1	General Note.....	10
2.2	Intended Use.....	10
2.3	Personnel Qualification .....	10
2.4	Personal Injury .....	11
2.4.1	Communication Stop .....	11
2.4.2	Mismatching System Configuration.....	11
2.5	Property Damage .....	12
2.5.1	Communication Stop .....	12
2.5.2	Invalid Firmware .....	12
2.5.3	Mismatching System Configuration.....	12
2.6	Labeling of Safety Messages .....	13
2.7	References Safety.....	13
3	NETDEVICE AND NETPROJECT .....	14
3.1	netDevice .....	14
3.1.1	netDevice - Network View .....	15
3.1.2	netDevice – Topology Editor .....	17
3.1.3	netDevice - Device Catalog.....	18
3.2	netProject - Network.....	21
4	WORKING WITH THE MENUS.....	22
4.1	The Menu Bar .....	22
4.2	Menu Device and Context Menu .....	22
4.3	Online Functions via the Context Menu.....	25
4.3.1	Debug Mode .....	25
4.3.2	Cut/Copy/Paste .....	26
4.3.3	Network Scan .....	26
4.3.4	Topology Editor .....	26
4.3.5	Additional Functions .....	27
4.3.6	Additional Functions > Service > Start /Stop Communication .....	27
4.3.7	Delete .....	28

4.3.8	Change Symbolic Name.....	28
4.4	Menu Network.....	29
4.4.1	netDevice Network Toolbar .....	30
4.4.2	netDevice Debug Toolbar.....	30
5	WORKING WITH NETDEVICE AND NETPROJECT .....	31
5.1	Getting Started - Configuration Steps.....	31
5.2	Safety Messages on Firmware or Configuration Download .....	34
5.3	The Device Catalog.....	36
5.3.1	Load Device Catalog .....	36
5.3.2	Reload Device Catalog.....	36
5.3.3	Devices of other Vendors .....	37
5.4	Installing Slave DTM or adding Device Description .....	38
5.5	PROFINET IO Device Instance .....	39
5.6	Insert Device in Project .....	40
5.7	Cutting, copying, pasting Slave Devices.....	41
5.7.1	Enlarging Project Configuration.....	41
5.8	Delete Device from Project.....	42
5.9	Working with Buslines .....	43
5.9.1	Description of the Buslines.....	43
5.9.2	Add / Remove Busline.....	44
5.9.3	Arrange Elements in the Network View.....	45
5.9.4	Multiselection.....	46
6	CONFIGURATION .....	47
6.1	Online/Offline Configuration .....	47
6.2	Connect/disconnect Device .....	48
6.2.1	Download to Device.....	49
6.2.2	Upload from Device .....	49
7	APPENDIX .....	50
7.1	User Rights .....	50
7.2	List of Figures .....	51
7.3	List of Tables.....	51
7.4	Glossary.....	52
7.5	Contacts.....	53

# 1 Introduction

## 1.1 About this Manual

**netDevice** is a **FDT Container** for the configuration of field devices of different manufacturers.

### 1.1.1 Overview

The table below gives an overview of the descriptions provided in this manual:

Chapter	Section	Manual Page
netDevice and netProject	<i>netDevice</i>	14
	<i>netProject - Network</i>	21
Working with the Menus	<i>The Menu Bar</i>	22
	<i>Menu Device and Context Menu</i>	22
	<i>Menu Network</i>	29
Working with netDevice and netProject	<i>Getting Started - Configuration Steps</i>	31
	<i>The Device Catalog</i>	36
	<i>Installing Slave DTM or adding Device Description</i>	38
	<i>Insert Device in Project</i>	40
	<i>Cutting, copying, pasting Slave Devices</i>	41
	<i>Delete Device from Project</i>	42
	<i>Working with Buslines</i>	43
Configuration	<i>Online/Offline Configuration</i>	47
	<i>Connect/disconnect Device</i>	48

Table 1: Overview

### 1.1.2 Online Help

**netDevice** contains an integrated online help facility.

- To open the online help, select **Help > Content and Index** or press the **F1** key.

### 1.1.3 List of Revisions

Index	Date	Version	Component	Chapter	Revision
12	15-12-08	1.2000.x.x	AxSyconu.ocx	2, 3.1.2 4.2, 4.3.4, 5.1, 5.2	Chapter <i>Safety</i> added. Section <i>netDevice – Topology Editor</i> added, Section <i>Menu Device and Context Menu</i> revised and completed (a. o. 'Topology editor'). Section <i>Topology Editor</i> added. Section <i>Getting Started - Configuration Steps</i> , 'Topology editor' added Section <i>Safety Messages on Firmware or Configuration Download</i> added.
13	16-08-31	1.2000.x.x and 1.2100.x.x	AxSyconu.ocx	All	Update according to the current state of the graphical user interface. Terminology change: 'network view' instead of 'graphical network view'
14	17-02-24	1.2000.x.x and 1.2100.x.x	AxSyconu.ocx	-	Windows 8.1 and Windwos 10

### 1.1.4 Conventions in this Manual

Notes, operation instructions and results of operation steps are marked as follows:

#### Notes



**Important:** <important note you must follow to avoid malfunction>



**Note:** <general note>



<note, where to find further information>

#### Operation Instructions

1. <instruction>

2. <instruction>

or

➤ <instruction>

#### Results

↻ <result>

## 1.2 Legal Notes

### Copyright

© Hilscher Gesellschaft für Systemautomation mbH

All rights reserved.

The images, photographs and texts in the accompanying materials (in the form of a user's manual, operator's manual, Statement of Work document and all other document types, support texts, documentation, etc.) are protected by German and international copyright and by international trade and protective provisions. Without the prior written consent, you do not have permission to duplicate them either in full or in part using technical or mechanical methods (print, photocopy or any other method), to edit them using electronic systems or to transfer them. You are not permitted to make changes to copyright notices, markings, trademarks or ownership declarations. Illustrations are provided without taking the patent situation into account. Any company names and product designations provided in this document may be brands or trademarks by the corresponding owner and may be protected under trademark, brand or patent law. Any form of further use shall require the express consent from the relevant owner of the rights.

### Important notes

Utmost care was/is given in the preparation of the documentation at hand consisting of a user's manual, operating manual and any other document type and accompanying texts. However, errors cannot be ruled out. Therefore, we cannot assume any guarantee or legal responsibility for erroneous information or liability of any kind. You are hereby made aware that descriptions found in the user's manual, the accompanying texts and the documentation neither represent a guarantee nor any indication on proper use as stipulated in the agreement or a promised attribute. It cannot be ruled out that the user's manual, the accompanying texts and the documentation do not completely match the described attributes, standards or any other data for the delivered product. A warranty or guarantee with respect to the correctness or accuracy of the information is not assumed.

We reserve the right to modify our products and the specifications for such as well as the corresponding documentation in the form of a user's manual, operating manual and/or any other document types and accompanying texts at any time and without notice without being required to notify of said modification. Changes shall be taken into account in future manuals and do not represent an obligation of any kind, in particular there shall be no right to have delivered documents revised. The manual delivered with the product shall apply.

Under no circumstances shall Hilscher Gesellschaft für Systemautomation mbH be liable for direct, indirect, ancillary or subsequent damage, or for any loss of income, which may arise after use of the information contained herein.

### Liability disclaimer

The hardware and/or software was created and tested by Hilscher Gesellschaft für Systemautomation mbH with utmost care and is made available as is. No warranty can be assumed for the performance or

flawlessness of the hardware and/or software under all application conditions and scenarios and the work results achieved by the user when using the hardware and/or software. Liability for any damage that may have occurred as a result of using the hardware and/or software or the corresponding documents shall be limited to an event involving willful intent or a grossly negligent violation of a fundamental contractual obligation. However, the right to assert damages due to a violation of a fundamental contractual obligation shall be limited to contract-typical foreseeable damage.

It is hereby expressly agreed upon in particular that any use or utilization of the hardware and/or software in connection with

- Flight control systems in aviation and aerospace;
- Nuclear fusion processes in nuclear power plants;
- Medical devices used for life support and
- Vehicle control systems used in passenger transport

shall be excluded. Use of the hardware and/or software in any of the following areas is strictly prohibited:

- For military purposes or in weaponry;
- For designing, engineering, maintaining or operating nuclear systems;
- In flight safety systems, aviation and flight telecommunications systems;
- In life-support systems;
- In systems in which any malfunction in the hardware and/or software may result in physical injuries or fatalities.

You are hereby made aware that the hardware and/or software was not created for use in hazardous environments, which require fail-safe control mechanisms. Use of the hardware and/or software in this kind of environment shall be at your own risk; any liability for damage or loss due to impermissible use shall be excluded.

## Warranty

Hilscher Gesellschaft für Systemautomation mbH hereby guarantees that the software shall run without errors in accordance with the requirements listed in the specifications and that there were no defects on the date of acceptance. The warranty period shall be 12 months commencing as of the date of acceptance or purchase (with express declaration or implied, by customer's conclusive behavior, e.g. putting into operation permanently).

The warranty obligation for equipment (hardware) we produce is 36 months, calculated as of the date of delivery ex works. The aforementioned provisions shall not apply if longer warranty periods are mandatory by law pursuant to Section 438 (1.2) BGB, Section 479 (1) BGB and Section 634a (1) BGB [Bürgerliches Gesetzbuch; German Civil Code] If, despite of all due care taken, the delivered product should have a defect, which already existed at the time of the transfer of risk, it shall be at our discretion to either repair the product or to deliver a replacement product, subject to timely notification of defect.

The warranty obligation shall not apply if the notification of defect is not asserted promptly, if the purchaser or third party has tampered with the products, if the defect is the result of natural wear, was caused by unfavorable operating conditions or is due to violations against our

operating regulations or against rules of good electrical engineering practice, or if our request to return the defective object is not promptly complied with.

### **Costs of support, maintenance, customization and product care**

Please be advised that any subsequent improvement shall only be free of charge if a defect is found. Any form of technical support, maintenance and customization is not a warranty service, but instead shall be charged extra.

### **Additional guarantees**

Although the hardware and software was developed and tested in-depth with greatest care, Hilscher Gesellschaft für Systemautomation mbH shall not assume any guarantee for the suitability thereof for any purpose that was not confirmed in writing. No guarantee can be granted whereby the hardware and software satisfies your requirements, or the use of the hardware and/or software is uninterrupted or the hardware and/or software is fault-free.

It cannot be guaranteed that patents and/or ownership privileges have not been infringed upon or violated or that the products are free from third-party influence. No additional guarantees or promises shall be made as to whether the product is market current, free from deficiency in title, or can be integrated or is usable for specific purposes, unless such guarantees or promises are required under existing law and cannot be restricted.

### **Confidentiality**

The customer hereby expressly acknowledges that this document contains trade secrets, information protected by copyright and other patent and ownership privileges as well as any related rights of Hilscher Gesellschaft für Systemautomation mbH. The customer agrees to treat as confidential all of the information made available to customer by Hilscher Gesellschaft für Systemautomation mbH and rights, which were disclosed by Hilscher Gesellschaft für Systemautomation mbH and that were made accessible as well as the terms and conditions of this agreement itself.

The parties hereby agree to one another that the information that each party receives from the other party respectively is and shall remain the intellectual property of said other party, unless provided for otherwise in a contractual agreement.

The customer must not allow any third party to become knowledgeable of this expertise and shall only provide knowledge thereof to authorized users as appropriate and necessary. Companies associated with the customer shall not be deemed third parties. The customer must obligate authorized users to confidentiality. The customer should only use the confidential information in connection with the performances specified in this agreement.

The customer must not use this confidential information to his own advantage or for his own purposes or rather to the advantage or for the purpose of a third party, nor must it be used for commercial purposes and this confidential information must only be used to the extent provided for in this agreement or otherwise to the extent as expressly authorized by the disclosing party in written form. The customer has the right, subject to the obligation to confidentiality, to disclose the terms and conditions of this agreement directly to his legal and financial consultants as would be required for the customer's normal business operation.



### Export provisions

The delivered product (including technical data) is subject to the legal export and/or import laws as well as any associated regulations of various countries, especially such laws applicable in Germany and in the United States. The products / hardware / software must not be exported into such countries for which export is prohibited under US American export control laws and its supplementary provisions. You hereby agree to strictly follow the regulations and to yourself be responsible for observing them. You are hereby made aware that you may be required to obtain governmental approval to export, reexport or import the product.

## 1.3 Registered Trademarks

Windows® XP, Windows® Vista, Windows® 7, Windows® 8, Windows® 8.1 and Windows® 10 are registered trademarks of Microsoft Corporation.

CANopen® is a registered trademark of CAN in AUTOMATION - International Users and Manufacturers Group e.V (CiA), Nürnberg.

CC-Link is a registered trademark of Mitsubishi Electric Corporation, Tokyo, Japan.

CompoNet™, DeviceNet™ and EtherNet/IP™ are trademarks of ODVA (Open DeviceNet Vendor Association, Inc).

EtherCAT® is a registered trademark and a patented technology of Beckhoff Automation GmbH, Verl, Germany, formerly Elektro Beckhoff GmbH.

Modbus is a registered trademark of Schneider Electric.

POWERLINK is a registered trademark of B&R, Bernecker + Rainer Industrie-Elektronik Ges.m.b.H, Eggelsberg, Austria

PROFIBUS® und PROFINET® are registered trademarks of PROFIBUS International, Karlsruhe.

Sercos and Sercos interface are registered trademarks of Sercos international e. V., Suessen, Germany.

All other mentioned trademarks are property of their respective legal owners.

## 2 Safety

### 2.1 General Note

The documentation in the form of a user manual, an operating instruction manual or other manual types, as well as the accompanying texts have been created for the use of the products by educated personnel. When using the products, all Safety Messages, Integrated Safety Messages, Property Damage Messages and all valid legal regulations must be obeyed. Technical knowledge is presumed. The user has to assure that all legal regulations are obeyed.

### 2.2 Intended Use

**netDevice** is a **FDT Containe** which serves for the configuration of field devices of different manufacturers.

### 2.3 Personnel Qualification

Personnel responsible for the application of the network system shall be aware of the system behavior and shall be trained in using the system.

## 2.4 Personal Injury

To ensure your own personal safety and to avoid personal injury, you necessarily must read, understand, and comply with the safety instructions and safety messages in this manual before you configure your system.

### 2.4.1 Communication Stop

If you perform a firmware download or a configuration download via the Master DTM or the Slave DTM (stand alone Slave at the root bus line) be aware of the following:

- Together with the firmware download, an automated device reset is performed that will interrupt all network communications and established connections will drop.
- If you attempt to download the configuration during bus operation, the communication between Master and Slaves is stopped.
- Unexpected equipment operation may cause personal injury.
- Stop the application program before starting upgrading the firmware or downloading the configuration.
- Make sure that your equipment operates under conditions that prevent personal injury. All network devices should be placed in a fail-safe mode before upgrading the firmware or downloading a configuration.

Detailed description about the firmware and configuration download you find in the operation instruction manual of the DTM.

### 2.4.2 Mismatching System Configuration

Mismatching system configuration loaded into the device could result in faulty data mapping in the application program and thus unexpected equipment operation may cause personal injury.

## 2.5 Property Damage

To avoid property damage respectively device destruction and damage to your system or to your equipment, you necessarily must read, understand and follow the following safety instructions and safety messages in this manual about danger causing property damage, before you configure your system.

### 2.5.1 Communication Stop

If you perform a firmware download or a configuration download via the Master DTM or the Slave DTM (stand alone Slave at the root bus line) be aware of the following:

- Together with the firmware download, an automated device reset is performed that will interrupt all network communications and established connections will drop.
- If you attempt to download the configuration during bus operation, the communication between Master and Slaves is stopped.

#### **Damage of Equipment**

- Unexpected equipment operation may cause property damage.
- Stop the application program before starting upgrading the firmware or downloading the configuration.
- Make sure that your equipment operates under conditions that prevent property damage. All network devices should be placed in a fail-safe mode before upgrading the firmware or downloading a configuration.

#### **Loss of Device Parameters**

- Both the firmware download and the configuration download erase the configuration data base. The firmware download overwrites the existing firmware in the network device.
- Device parameters that have not been saved non-volatile are getting lost during the reset.
- To complete the firmware update and to make the device operable again, re-download the configuration when the firmware update has been finished.

Detailed description about the firmware and configuration download you find in the operation instruction manual of the DTM.

### 2.5.2 Invalid Firmware

Loading invalid firmware files could render your module unusable.

### 2.5.3 Mismatching System Configuration

Mismatching system configuration loaded into the device could result in faulty data mapping in the application program and thus unexpected equipment operation may cause damage of equipment.

## 2.6 Labeling of Safety Messages

- The **Section Safety Messages** at the beginning of a chapter are pinpointed particularly and highlighted by a signal word according to the degree of endangerment. The kind of danger is specified exactly by the safety message text
- The **Integrated Safety Messages** within an instruction description are highlighted with a signal word according to the degree of endangerment. The kind of danger is specified exactly by the safety message text.




Signal Word	Meaning (international)	Meaning (USA)
 <b>DANGER</b>	Indicates a direct hazard with high risk, which will have as consequence death or grievous bodily harm if it isn't avoided.	Indicates a Hazardous Situation Which if not Avoided, will Result in Death or Serious Injury.
 <b>WARNING</b>	Indicates a possible hazard with medium risk, which will have as consequence death or (grievous) bodily harm if it isn't avoided.	Indicates a Hazardous Situation Which if not Avoided, could Result in Death or Serious Injury.
 <b>CAUTION</b>	Indicates a minor hazard with medium risk, which could have as consequence simple battery if it isn't avoided.	Indicates a Hazardous Situation Which if not Avoided, may Result in Minor or Moderate Injury.

Table 2: Signal Words in Safety Messages on Personal Injury


Signal Word	Meaning (international and USA)
 <b>NOTICE</b>	Indicates a Property Damage Message.

Table 3: Signal Words in Safety Messages on Property Damage

In this document all Safety Instructions and Safety Messages are designed according both to the international used safety conventions as well as to the ANSI Z535.6 standard, refer to reference safety [S1].

In this document the signal words 'WARNING', 'CAUTION' and 'NOTICE' are used according to ANSI Z535.6 standard. The meaning given in ISO/IEC 26514 [S4] section '11.11 Contents of warnings and cautions' is not relevant in this manual.

## 2.7 References Safety

- [S1] ANSI Z535.6-2006 American National Standard for Product Safety Information in Product Manuals, Instructions, and Other Collateral Materials
- [S4] 26514-2010 - IEEE Standard for Adoption of ISO/IEC 26514:2008 Systems and Software Engineering--Requirements for Designers and Developers of User Documentation

## 3 netDevice and netProject

### 3.1 netDevice

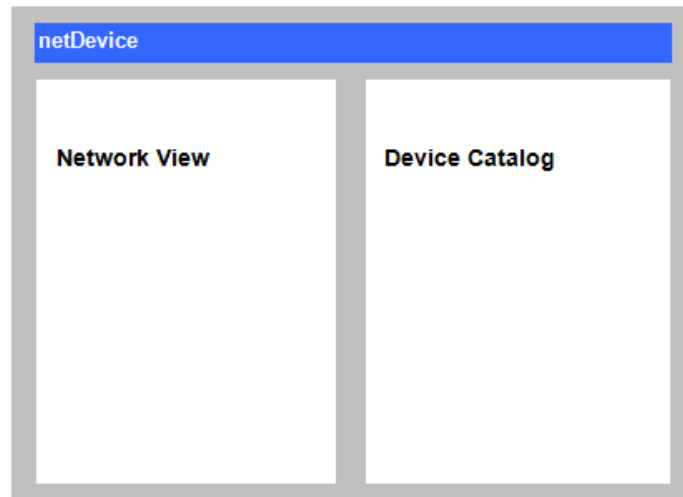


Figure 1: netDevice - Network View and Device Catalog (Principle)

The **netDevice** window is divided in two different areas:

- **Network View**

The left side of the **netDevice** window shows the current configuration as network view. In the network view you can arrange the single elements (devices and bus lines). A detailed description of the network view you find in section *netDevice - Network View* on page 15.

- **Device Catalog**

The right side of the **netDevice** window displays the installed devices as tree structure. Further information about this you find in section *netDevice - Device Catalog* on page 15.

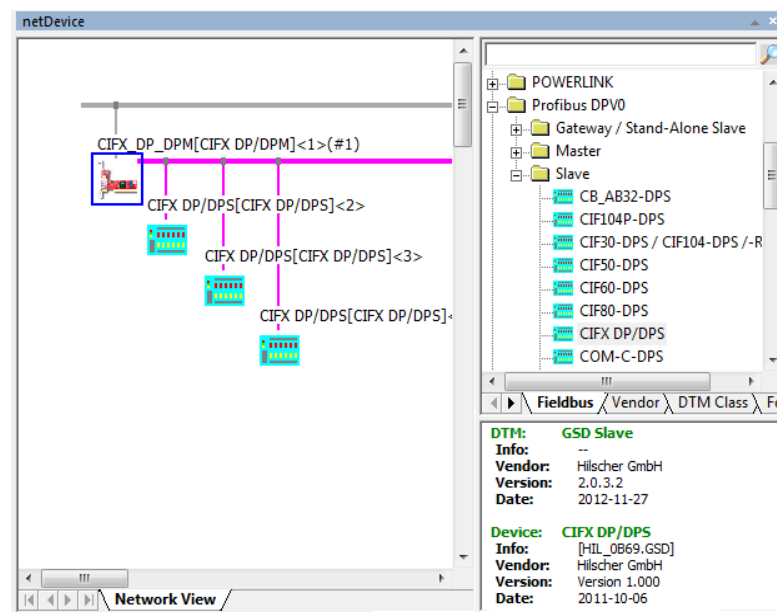


Figure 2: Example for netDevice - Network View and Device Catalog

### 3.1.1 netDevice - Network View

The network view displays the current project as graphical network structure. Devices can be added by drag and drop from the device catalog and they are displayed as an icon in the network view. For further information refer to section *Insert Device in Project* on page 40 or to section *Arrange Elements in the Network View* on page 45.

- **Device Symbol and Device Description**

Above or below the device icon the name of the device with the device address are displayed and for master devices a continuous number, the network ID. The position of the text depends on the direction of the connection line.

- **Context Menu**

By a right mouse click on a device icon, the context menu is opened. The context menu contains all entries of the menu **Device** from the menu bar of the frame application. The context menu contains further entries for configuration and diagnosis. A detailed description about the **Device** menu and the context menu you find in section *Menu Device and Context Menu* on page 22.

- **Configuration Dialog**

For most of the DTM the configuration dialog of the appropriate device opens by a double click on a device icon. Otherwise the context menu is opened. In the configuration dialog all device and bus-specific settings can be made. The possibilities of the configuration are manufacturer specific. Closer information for device configuration can be taken from the technical manual of the manufacturer.

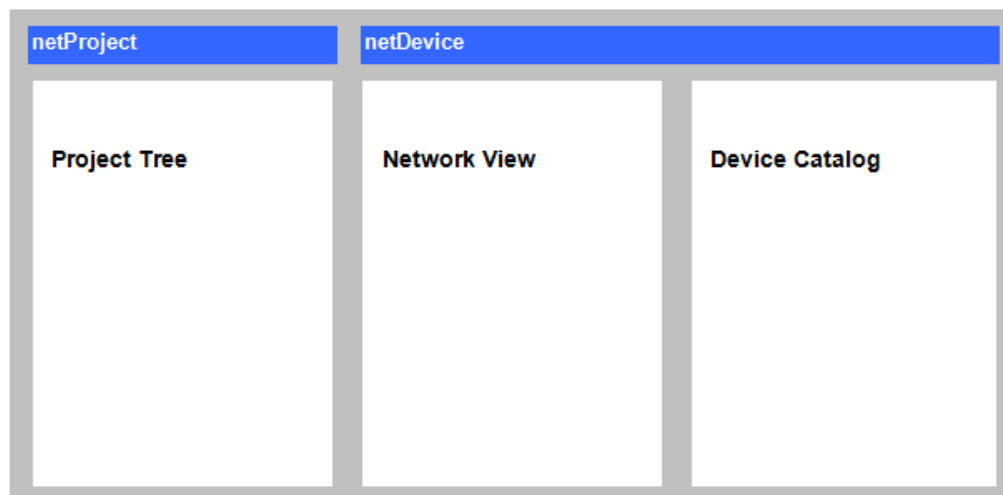


Figure 3: netDevice and netProject - Network View (Principle)

The network view in the **netDevice** window is synchronized with the **netProject** window. That means devices which you insert

- in the network view, are also displayed automatically in the **netProject** window.
- in the **netProject** window, are shown in the network view of the **netDevice** window.

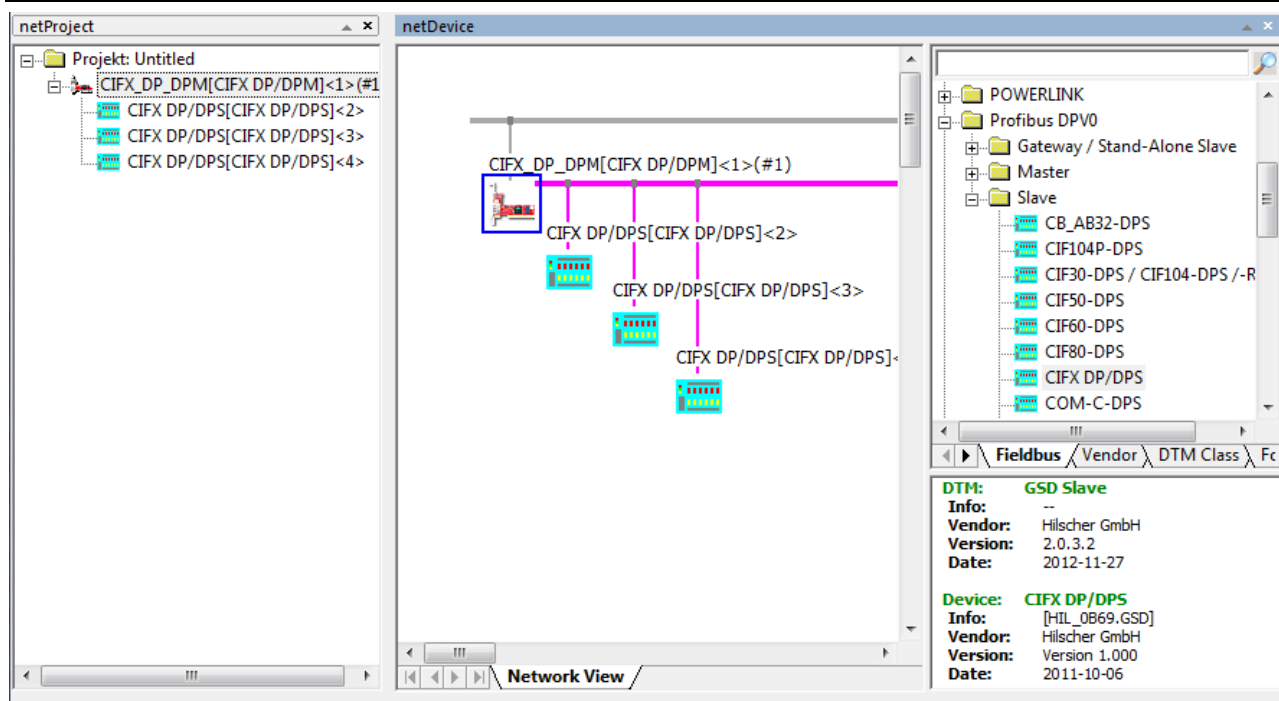


Figure 4: Example for netDevice and netProject - Network View

### 3.1.1.1 Notation of the Device Description

The device description is composed as follows:

YYYYY [XXXX] <1> (#1)	
YYYYY	Symbolic Name
[XXXX]	Device Description
<1>	Station Address
(#1)	Network ID

Figure 5: Notation of the Device Description

Term	Description
<b>Symbolic Name</b>	In the <b>Symbolic Name</b> dialog optionally a symbolic name can be entered. This name is displayed in netDevice and netProject as the first part of the device description. For further information refer to section <i>Change Symbolic Name</i> on page 28.
<b>Device Description</b>	The <b>Device Description</b> indicates the name of the device and can not be edited. For PROFINET IO in the device catalog under 'Stand-Alone-Slave' or 'Slave' all device instances that derive from the same device description file, appear as separate devices.
<b>Station Address</b>	The <b>Station Address</b> is the device address on the bus and can be changed in the Master DTM configuration dialog.
<b>Network ID</b>	The <b>Network ID</b> is the network address of the Master and it is provided automatically when inserting the device. The network ID is static and cannot be changed. For Slaves no network ID appears.

Table 4: Notation of the Device Description



### 3.1.2 netDevice – Topology Editor

The Hilscher Topology Editor supports the configuration of a device topology (network structure), including the connections between devices and the related device, port and connection settings. The Topology Editor can be used for the configuration of different real-time-Ethernet systems.



For information concerning the configuration of the topology refer to the Operating instruction manual *Topology Editor*.

### 3.1.3 netDevice - Device Catalog

The device catalog displays a list of devices of all DTM installed on this PC. If the device catalog is loaded, it is shown as tree structure in the **netDevice** window.

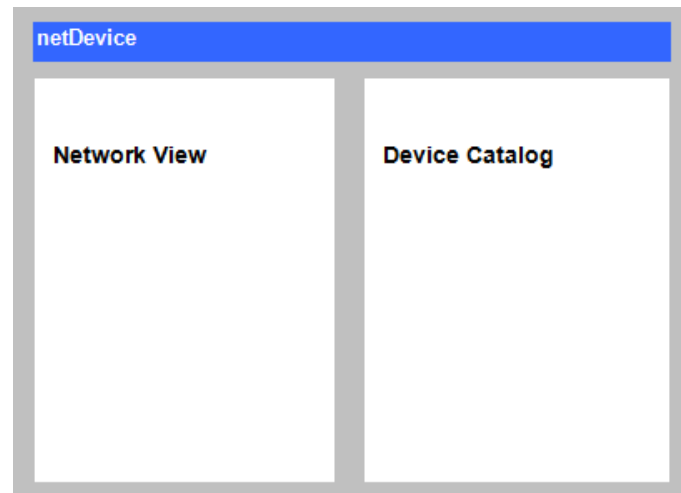


Figure 6: netDevice - Device Catalog (Principle)

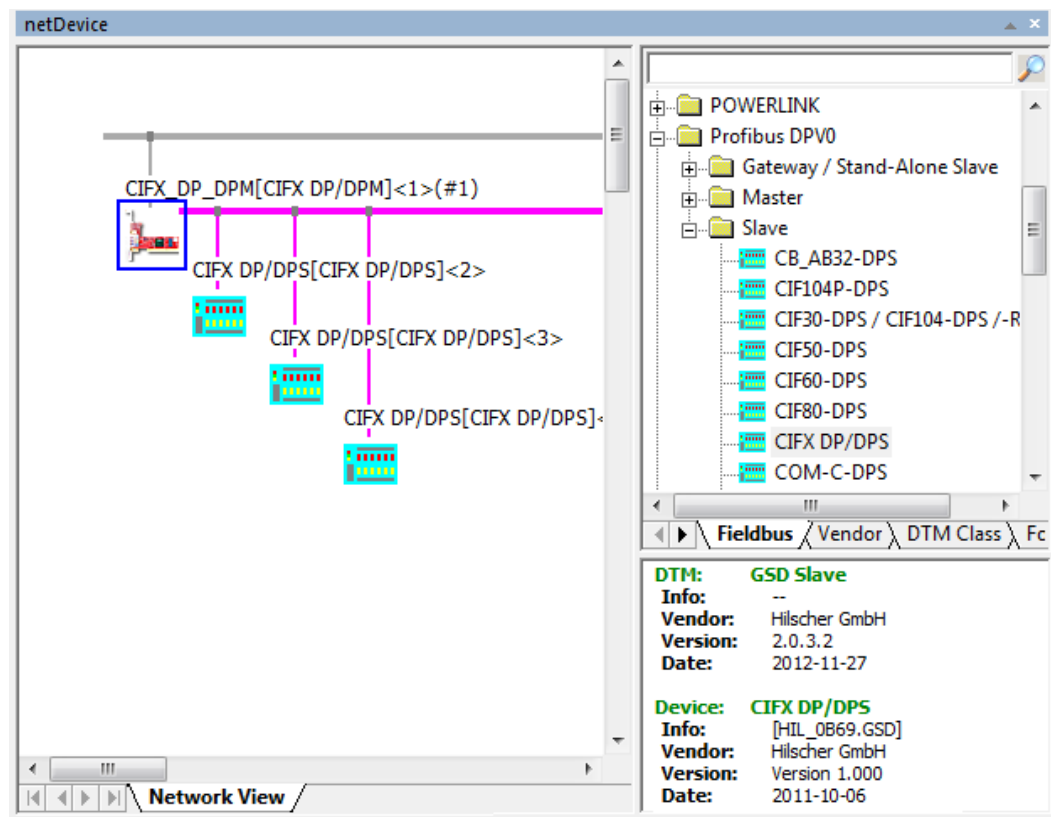


Figure 7: Example for netDevice - Network View and Device Catalog

Selecting a register card, the devices are arranged by different criteria, e. g. by **Vendor**, **Fieldbus** or **DTM Class**.

Further information about working with the device catalog you find in section *The Device Catalog* on page 36.

### 3.1.3.1 Search Function in the Device Catalog

Using the search function in the device catalog, you can search for devices. You can search by device name or any combination of characters.



**Note:** Do not use wildecards.

- Select the **Found** tab.

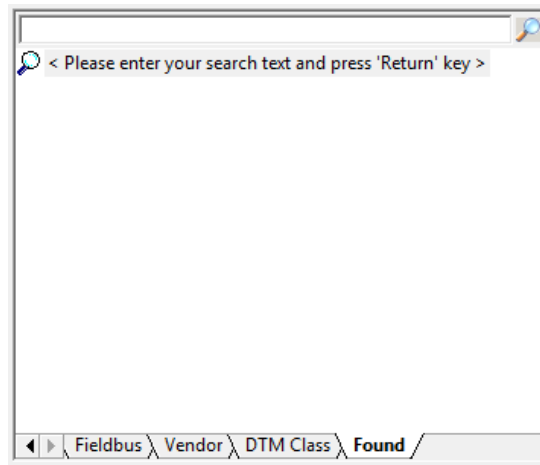


Figure 8: Search Function in the Device Catalog

- Enter the search text in the search window, for example "COMX".
- Press **Return**.
- All devices that contain the code "COMX" in the name are displayed.

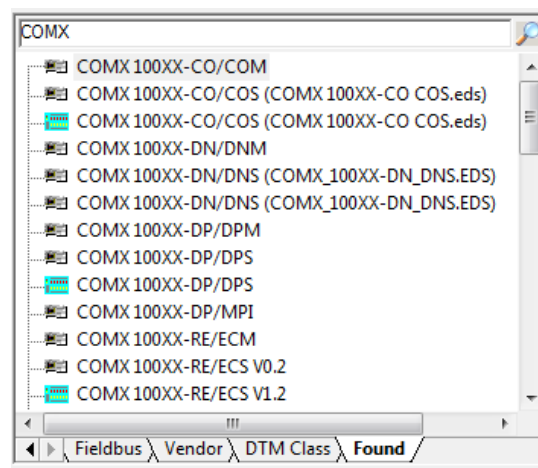


Figure 9: Search Function in the Device Catalog – Search Result

### 3.1.3.2 Notations to the DTM and to the Device

In the lower part of the device catalog window appears detailed information about the selected device and DTM. This includes the *DTM Name*, the *Device Name* as well as information about the **Vendor**, the **Version** and the **Date**. This information will help you to distinguish Master devices of different manufacturers that appear in the device catalog under the same name, based on their hardware revision or in reference to the date of manufacture. Under **Info** information such as *firmware version*, the *feature set* or the *device description file name* appears, you will need for the PROFINET IO ,Stand-Alone Slave' (Device) and ,Slave' (Generic Device) to select the device instance.

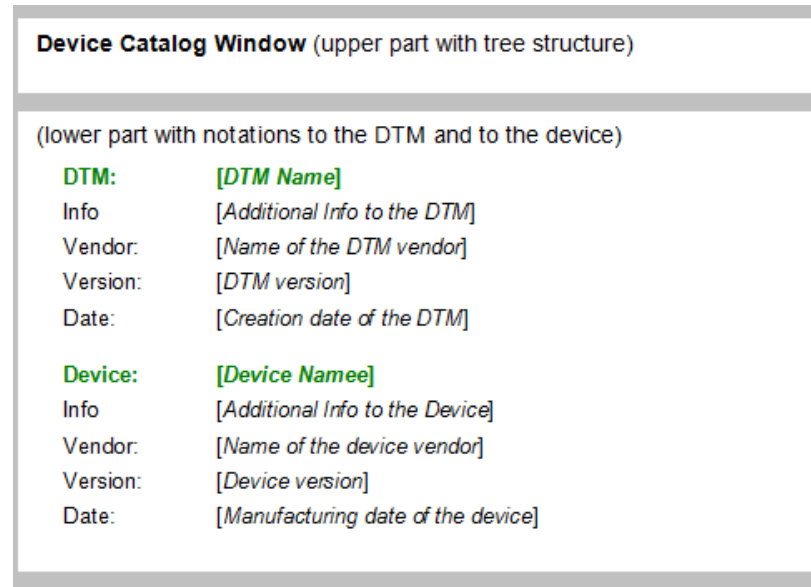


Figure 10: netDevice - Device Catalog - Notations to the DTM and to the Device (Principle)

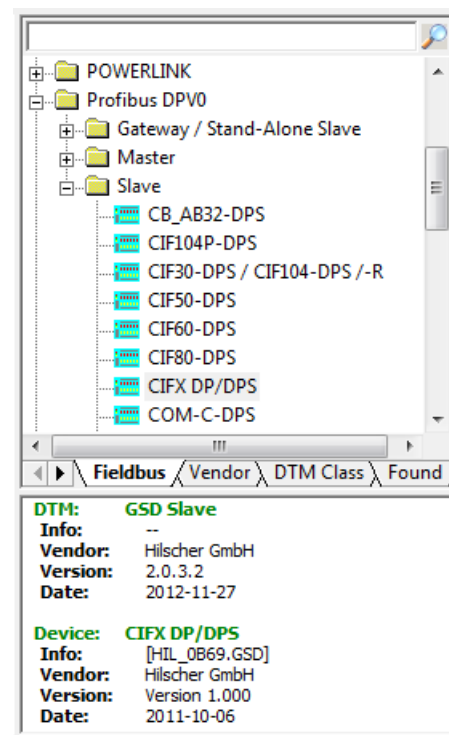


Figure 11: Example for netDevice - Device Catalog

## 3.2 netProject - Network

In the **netProject** the current configuration is displayed as project tree. Besides the device icon the name of the device and the device address are shown. For Master devices additionally a continuous number is displayed, the network ID.

The context menu of a device is opened by a right mouse click on the device icon. Here via **Configuration** the configuration dialog of the DTM can be accessed.

Via a double click on a device icon the configuration dialog of the DTM is opened, if supported by the DTM. In the configuration dialog then the parameter and general settings can be made.

Devices which are inserted in the network view are also displayed in the netProject and the other way, too.

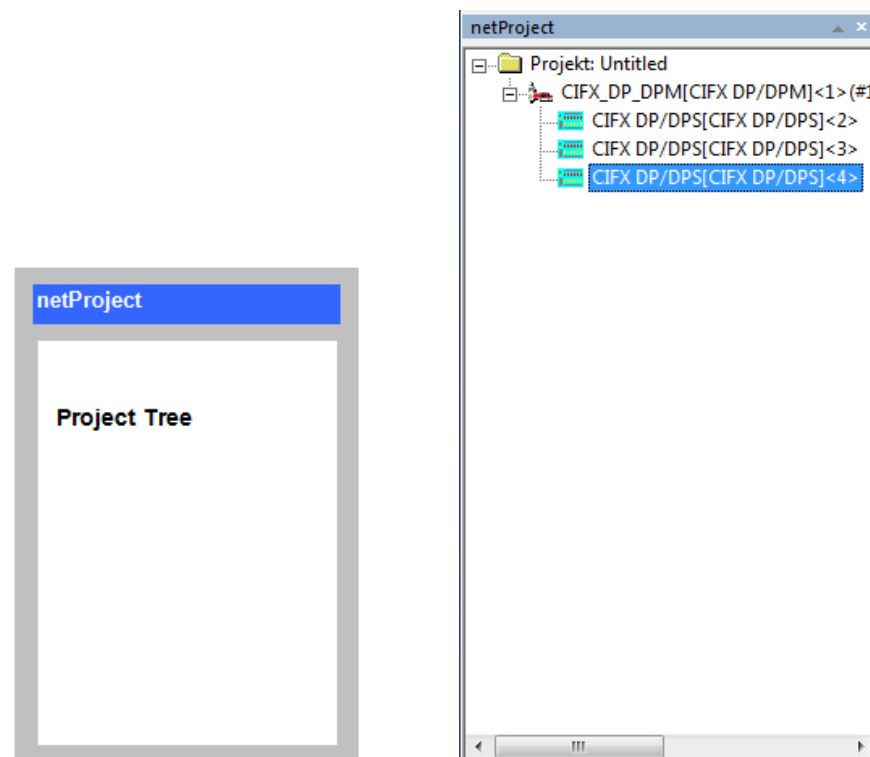


Figure 12: netProject (Principle) (left side), Example (right side)

The current selection in the **netProject** window is synchronized with the network view. More about multiselection you find in section on page 46.

## 4 Working with the Menus

### 4.1 The Menu Bar

The both menus **Device** and **Network** are displayed in the menu bar of the frame application, if one of the windows **netProject** or **netDevice** is activated. The menu **Network** is a dynamic menu.

### 4.2 Menu Device and Context Menu

The menu **Device** can be selected via the menu bar of the frame application.

The **context menu** can be opened via right click on the device icon in the netDevice network view.

Both menus contain several entries in common. Entries which are greyed out are disabled for the selected device. Possibly some entries are not supported by the device.

Selecting via	Description
Menu <b>Device</b>	The menu <b>Device</b> in the menu bar of the frame application includes the entries <b>Connect/Disconnect</b> , <b>Download/Upload</b> , <b>Configuration</b> , <b>Measured Value</b> , <b>Simulation</b> and <b>Diagnosis*</b> (*only Master and/or Gateway/Stand-Alone Slaves).
Context menu (Right mouse click on the device icon)	Additionally to the entries in the menu <b>Device</b> the context menu contains the entries <b>Cut/Copy/Paste</b> (enabled only for Slave devices), <b>Additional Functions</b> , <b>Delete</b> and <b>Symbolic Name</b> and for Master devices if so <b>Start Debug Mode</b> , <b>Topology editor</b> and <b>Network Scan ...</b> . . For more refer to section <i>Online Functions via the Context Menu</i> on page 25. The context menu can contain additional manufacturer specific entries. They are not specified here.

Table 5: Menu Device and Context Menu



For further information to the configuration and diagnosis possibilities of a certain device, open the device specific help file.

To open the help file, select **Help** in the DTM dialog or press the **F1** key or refer to the manual of the installed DTM.

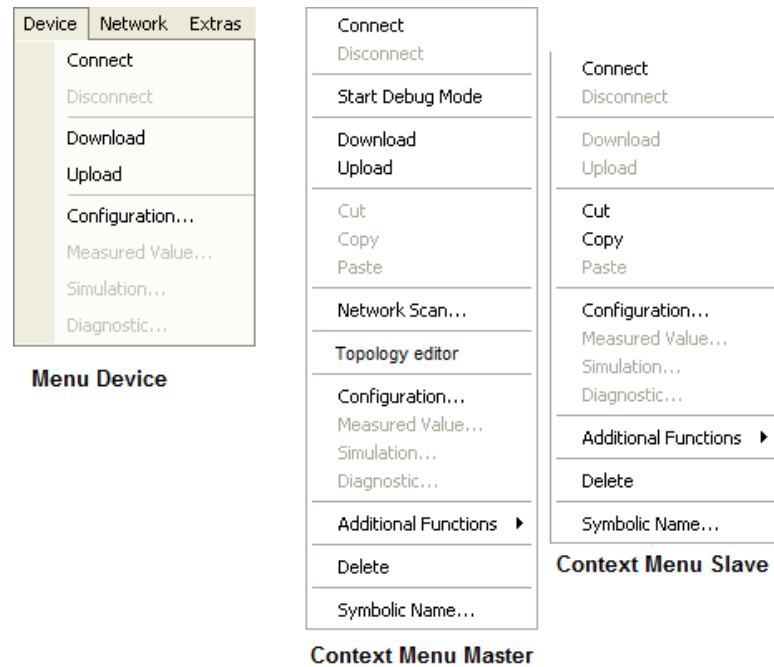


Figure 13: Menu Device (left), Example Context Menu for Master or Slave (right)



**Note:** The **context menu** can have additional or less entries as described here, depending by software variant.

In the following table you find a description of the entries of the menu **Device** and the further entries of the **context menu**.

Menu	Meaning
<b>Connect</b> <sup>1</sup>	<p>Via <b>Connect</b> a connection from the DTM (application program) to the selected device is established.</p> <p>When the user connects a Master device, only this device is connected. When the user connects a Slave device, the Slave device is connected via the communication channel of the Master. Thus, the Master is also connected online.</p> <p>If a device is connected, the name of the device in the network view in netDevice is marked in green. For dead times during the connection is established a yellow marking appears, which is not always visible depending by the system speed.</p> <p>For more refer to section <i>Connect/disconnect Device</i> on page 48.</p>
<b>Disconnect</b> <sup>1</sup>	<p>Via <b>Disconnect</b> the connection established from the DTM (application program) to the device is disconnected.</p> <p>When a Master is disconnected, the Slaves of this network get also disconnected.</p> <p>The name of the device is displayed without green background, if the device is disconnected.</p>
<b>Start Debug Mode</b> <sup>1</sup>	<p>You first must assign the device to the Master DTM, configure the Master or the Slave device parameters and download the configuration to the Master.</p> <p>Then via context menu &gt; <b>Start Debug Mode</b> the status of the cyclical communications between a Master and Slave devices can be identified based on the colors of the bus lines as well as the debug icons.</p> <p>For more refer to section <i>Debug Mode</i> on page 25.</p>
<b>Download</b> <sup>1</sup>	<p>Via <b>Download</b> the current configuration can be downloaded from the DTM (application program) into the device. For the configuration download a hardware must be assigned to the device in the application program.</p> <p><i>Adhere to the safety information applying for this command.</i></p> <p>For more refer to section <i>Download to Device</i> on page 49.</p>
<b>Upload</b> <sup>1</sup>	<p>Via <b>Upload</b> the configuration stored in the device can be uploaded to the DTM (application program). For the configuration upload the configuration must stored in the device and the DTM must provide the upload function. For the configuration upload the device must be connected to the DTM (application program).</p>

Menu	Meaning
	For more refer to section <i>Upload from Device</i> on page 49.
<b>Cut/Copy/Paste</b> <sup>1</sup>	Via <b>Cut/Copy/Paste</b> in the netDevice network view you can cut or copy one or multiple Slave devices at the Master bus line and paste them to this or to an other Master bus line. The Slave device configuration remains maintained and further configuration is not required. For more refer to section <i>Cutting, copying, pasting Slave Devices</i> on page 41.
<b>Network Scan ...</b>	Via <b>Network Scan ...</b> (if included) the current bus configuration is read back from the Slave devices. If for example the Master device is configured without a Slave in the netDevice network view at first, Slaves already available at the bus then can be inserted in the project via <b>Network Scan ...</b> For more refer to section <i>Network Scan</i> on page 26.
<b>Topology editor</b>	Via <b>Topology editor</b> (if included) the Toplogy editor is displayed. In addition to the device configuration in the DTM additional device and connection data (for the topology) can be displayed or configured in the Topology Editor. For more refer to section <i>Topology Editor</i> on page 26.
<b>Configuration</b>	Via <b>Configuration</b> the device parameters of the currently in the netDevice network view selected device are displayed. The device parameters are manufacturer specific and cannot be specified here. Also the view of the menu can vary depending by the DTM. <sup>2</sup>
<b>Measured Value</b>	Via <b>Measured Value</b> the measurement values of the device are shown, if supported by the DTM. <sup>2</sup>
<b>Simulation</b>	Via <b>Simulation</b> an offline simulation for this device is displayed if supported by the DTM. <sup>2</sup>
<b>Diagnosis</b>	Via <b>Diagnosis</b> the diagnosis dialog for this device is displayed if supported by the DTM and if an online diagnosis connection to the device has been established. The diagnosis functions are manufacturer specific. <sup>2</sup>
<b>Additional Functions</b>	The entries <b>Offline Compare...</b> , <b>Online Compare...</b> and <b>Setpoint Value</b> are not supported. In the submenu <b>Service</b> you can start or stop the communication. <i>Adhere to the safety information applying for these commands.</i> For more refer to section <i>Additional Functions &gt; Service &gt; Start /Stop Communication</i> on page 27 or section <i>Additional Functions</i> on page 27.
<b>Delete</b>	Via <b>Delete</b> the selected device is removed from the project. For more refer to section <i>Delete Device from Project</i> on page 42.
<b>Symbolic Name</b>	Here an arbitrary name can be assigned to the device. This name is displayed in netDevice and netProject as the first part of the device description. For more refer to section <i>Change Symbolic Name</i> on page 28.

Table 6: Menu Device

1



**Note:** The entries **Connect/Disconnect**, **Start Debug Mode**, **Download/Upload** and **Cut/Copy/Paste** are selectable for many devices. If these functions are supported by the selected device can only be seen after activating this menu. If they are not supported, an error will be reported.

<sup>2</sup> For further details refer to the manufacturer documentation.



## 4.3 Online Functions via the Context Menu

The **context menu** of the device contains all entries of the **Device** menu in the menu bar. Additionally there are further entries in the context menu:

### 4.3.1 Debug Mode



---

**Note:** Depending by the software variant of the DTM the **debug mode** is available or not.

---

The **debug mode** allows to identify the status of the cyclical communication between a Master device and its Slave devices on a network based on the colors of the bus lines as well as the debug icons.

For the Master device or the Master bus line this is valid:

- Master device in operation, cyclical communication runs. (Bus line **light green**)
- Master device not operable. (Bus line **blue**)
- Master in STOP state. (Bus line **red**)

For the Slave device or the bus line from the Master bus line to the Slave device this is valid:

- Slave device in operation, cyclical communication to the Master device runs. (Bus line **light green**)
- Diagnosis message available at the Master device. (Bus line **yellow** (yellow))
- Slave device not found during boot up. (Bus line **blue**)
- Error in the Slave-to-Master communication. (Bus line **red**)
- Slave device is not configured. (Bus line **gray**)



---

For details to the **debug mode** refer to the Operating Instruction Manual of the Master DTM.

---

### 4.3.2 Cut/Copy/Paste

Via the context menu entries **Cut**, **Copy** or **Paste** one or more Slave devices can be cut or copied in the **netDevice** network view at a Master bus line and then can be inserted at the same Master bus line or at another one. I. e. the Slave devices can be cut or copied at a Master bus line by selecting the Slave devices and using the **Cut** or **Copy** command from the context menu. Then the Slave devices can be inserted at the Master bus line by using the **Paste** command from the context menu. The configuration for the pasted Slave devices remains maintained.

A detailed description for the context menu entries **Cut**, **Copy** or **Paste** is given in section *Cutting, copying, pasting Slave Devices* on page 41.

### 4.3.3 Network Scan

The menu entry **Network Scan...** is displayed or not depending by the device.

With **Network Scan...** it is possible to find out automatically which types of Slave devices are attached to the Master device and how these devices are configured.

To scan the network structure, proceed as follows:

1. Select **Network Scan...** from the context menu (right mouse click).
- A window with data of the found devices is displayed.
2. Select the **Create Devices** button.



**Note:** For further information to **Network Scan** refer to the Operating Instruction Manual of the respective Master DTM.

### 4.3.4 Topology Editor

In the topology view (graphical view of the editor with the network structure), the IO devices can be connected to each other. Each link is represented as a line that begins at a device port and ends at the port of another device.

In the property views of the device, port and connection, the settings of the devices, ports and connections can be configured. Using this data, the Topology Editor checks the identity of the existing devices and whether a connection has been established.

The configuration data for the network structure, the devices and connections specified in the Topology Editor are transmitted to the master DTM where they are calculated and stored together with the master device configuration.



For information concerning the configuration of the topology refer to the Operating instruction manual *Topology Editor*.

### 4.3.5 Additional Functions

Menu Entry	Meaning
<b>Service</b>	In the submenu <b>Service</b> you can start or stop the communication. Refer to section <i>Additional Functions &gt; Service &gt; Start /Stop Communication</i> on page 27.
<b>Export</b>	In the submenu <b>Export</b> the current project data like project name, the fieldbus command structure and the device parameter are exported as CSV, DBM or XML file.
<b>Print</b>	The submenu <b>Print</b> contains the printing options of the DTM.
<b>Life List</b>	Information about the entries <b>Life List</b> , <b>Set Station Address</b> and <b>License</b> are provided in the Master DTM online-help.
<b>Set Station Address</b>	
<b>License</b>	

Table 7: Additional Functions



Depending by the software variant the context menu > **Additional Functions** can contain additional or less entries as described here. Further information to this is given in the help of the corresponding DTM.

### 4.3.6 Additional Functions > Service > Start /Stop Communication

You can manually start or stop the communication between a Master and Slaves.

- **Start Communication** is enabled, if the communication has been stopped before or if the configuration requires this (Controlled release of communication).
- **Stop Communication** is enabled, if the communication has been started.

To start or to stop the communication, proceed as follows:

*Adhere to the safety information applying for this commands.*

#### Start Communication

1. Connecting Device:



**Note:** To start the communication of the device at the bus manually, an online connection from the Master DTM to the Master device is required. Further information can be found in section *Connect/disconnect Device* on page 48.

2. Select **Additional Functions > Service > Start Communication** from the context menu (right mouse click).

➤ The device communicates at the bus.

#### Stop Communication

3. Select **Additional Functions > Service > Stop Communication** from the context menu (right mouse click).

➤ The communication of the device at the bus is stopped.

### 4.3.7 Delete

With the delete function a device is removed from the project. For further information see section *Delete Device from Project* on page 42.

### 4.3.8 Change Symbolic Name

Generally the **Device Description** as described under section *Notation of the Device Description* on page 16 is used as device name. Via **Symbolic Name** an additional name for the devices can be set.

➤ Right click on the device icon and select **Symbolic Name**.

⇒ The **Change Symbolic Name** dialog is displayed.

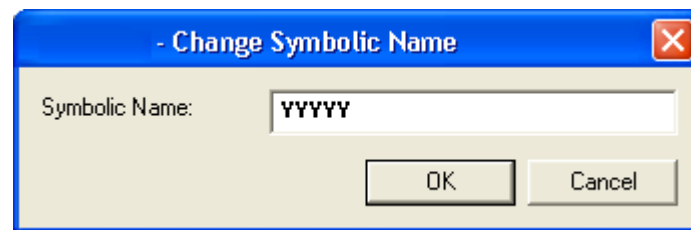


Figure 14: Change Symbolic Name

➤ Enter a symbolic name.

⇒ The used name then is displayed in the windows **netDevice** and **netProject** as name of the device.

The **Device Description** is always displayed in squared brackets behind the symbolic name.

YYYYY [XXXX] <1> (#1)	
YYYYY	Symbolic Name
[XXXX]	Device Description
<1>	Station Address
(#1)	Network ID

Figure 15: Notation of the Device Description

## 4.4 Menu Network

The menu **Network** includes the network depending entries

- Add Busline/Delete last Busline,
- Start/Stop Project Debug Mode,
- Device Catalog,
- Import Device Descriptions,
- Print Project Data.



**Note:** The menu entries **Add Busline** and **Remove last Busline** are independent from the connected hardware; it affects only the graphical view of the network created in the netDevice window. It does not affect the real hardware configuration.

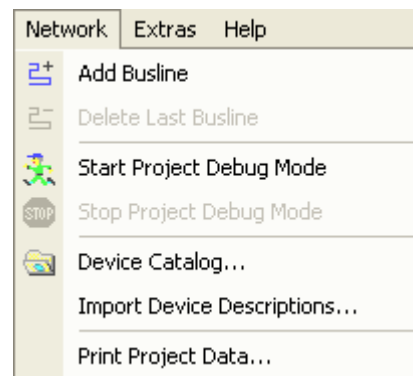


Figure 16: Menu Network

Menu	Meaning
<b>Add Busline</b>	Adds a busline to the selected bus in the netDevice window. A Master or a Master line must be selected.
<b>Delete last Busline</b>	Deletes the last added busline. A Master or a Master line must be selected.
<b>Start Project Debug Mode / Stop Project Debug Mode</b>	Via the <b>Start Project Debug Mode / Stop Project Debug Mode</b> function the debug mode for the entire project can be started or stopped. In the <b>Project Debug Mode</b> the status of the cyclical communication between the Master and Slave devices is displayed based on the colors of the bus lines as well as the debug icons.
<b>Device Catalog</b>	Selecting the <b>Device Catalog</b> function, the dialog of the device catalog opens. The device catalog can be loaded or if necessary reloaded. For more information about the device catalog refer to section <i>The Device Catalog</i> on page 36.
<b>Import Device Descriptions ...</b>	Via the <b>Import Device Descriptions ...</b> dialog a device can be added using a device description file. For more information refer to section <i>Installing Slave DTM or adding Device Description</i> on page 38.
<b>Print Project Data</b>	With the function <b>Print Project Data</b> the current project data like project name, the fieldbus command structure and the device parameters are printed out.

Table 8: Menu Network

### 4.4.1 netDevice Network Toolbar

The network toolbar is faded in and faded out via **View > Device**.

This toolbar contains the entries (from the left to the right):

- **Network > Add busline,**
- **Network > Delete Last busline** and
- **Network > Device Catalog**



Figure 17: netDevice Toolbar Network



**Note:** The **Network** toolbar is enabled, if the focus is put on the **netDevice** or **netProject** window.

### 4.4.2 netDevice Debug Toolbar



**Note:** The menu entries for the **debug mode** are only available, if the debug mode is supported by the frame application. Also, if **Start Project Debug Mode** is enabled, possibly some or all Master DTM in the project do not support the debug mode.

The debug toolbar is faded in and faded out via **View > Debug**.

This toolbar contains the entries (from the left to the right):

- **Debug > Start Project Debug Mode,**
- **Debug > Stop Project Debug Mode**



Figure 18: netDevice Debug Toolbar - Start Project Debug Mode



Figure 19: netDevice Debug Toolbar - Stop Project Debug Mode

## 5 Working with netDevice and netProject

### 5.1 Getting Started - Configuration Steps

The following table describes the steps to configure a Master device as it is typical for many cases. It is presupposed that the hardware installation was done.

The configuration for Master devices of different manufacturers may differ for some of the configuration steps of this example.

#	Step	Short Description	For detailed information see section	Page
1	Start Program	- Open the configuration software via <b>Start &gt; Programs</b> , - enter the user name and password in the dialog.	(See <i>Operating Instruction Manual of the Frame Application</i> )	-
2	Add Slave in the Device Catalog	Add the Slaves in the Device Catalog by importing the device description files to the Device Catalog. - <b>Network &gt; Import Device Descriptions</b> .	<i>Installing Slave DTM or adding Device Description</i>	38
3	Load device catalog	- select <b>Network &gt; Device Catalog</b> , - select button <b>Reload Catalog</b> . The Device Catalog is loaded automatically when the configuration software is opened.	<i>The Device Catalog</i>	36
4	Create new project	Depending of the frame application. For the configuration software: - select <b>File &gt; New</b> or <b>File &gt; Open</b> .	(See <i>Operating Instruction Manual of the Frame Application</i> )	-
5	Create Project Configuration	Insert Master or Slave into configuration: - In the Device Catalog click to the Master, - and insert the device via drag and drop <b>to the line</b> in the network view, - in the Device Catalog click to the Slave, - and insert the device via drag and drop <b>to the Master bus line</b> in the network view.	<i>Insert Device in Project</i>	40
6	Scan Network Structure	Alternatively scan the network structure: - Create the project configuration via context menu <b>Additional Functions &gt; Network Scan</b> . - Download the configuration to the Master device. - <i>Adhere to the safety information applying for this command.</i>	<i>Network Scan</i>	26
7	Enlarge Project Configuration	If necessary enlarge project configuration: - Therefore select Slave devices for enlargement. - Select context menu <b>Cut</b> and/or <b>Copy</b> . - Add Slave devices via context menu <b>Paste</b> . - Adapt Slave device address in the Master DTM configuration dialog.	<i>Multiselection, Cutting, copying, pasting Slave Devices, depends from device - (See help of the device manufacturer)</i>	41 46
8	Open the Master DTM configuration dialog	Open the Master DTM configuration dialog. - Double click to the device icon of the Master. - The Master DTM configuration dialog is displayed.	<i>depends from device - (See help of the device manufacturer)</i>	-
9	Select driver	In the Master DTM configuration dialog: - select <b>Settings &gt; Driver</b> , - select a driver. - if necessary, configure the driver settings.	<i>depends from device - (See help of the device manufacturer)</i>	-
10	Assign Master device (with or without firmware)	Assign the device to this driver. In the Master DTM configuration dialog: - select <b>Settings &gt; Device Assignment</b> ,	<i>depends from device - (See help of the device manufacturer)</i>	-

#	Step	Short Description	For detailed information see section	Page
		<ul style="list-style-type: none"> <li>- select a Master device,</li> <li>- select the button <b>Apply</b>.</li> </ul>		
11	Select and download firmware	<p>If not yet a firmware was loaded to the device. In the Master DTM configuration dialog:</p> <ul style="list-style-type: none"> <li>- select <b>Settings &gt; Firmware Download</b>,</li> <li>- select the button <b>Browse..</b>,</li> <li>- select a firmware file,</li> <li>- select the button <b>Open</b>,</li> <li>- select the buttons <b>Download</b> and <b>Yes</b>.</li> <li>- <i>Adhere to the safety information applying for this command.</i></li> </ul>	<i>depends from device - (See help of the device manufacturer)</i>	-
12	Assign Master device once more (with firmware and system channel) <i>For repeated download this step is omitted.</i>	<p>In the Master DTM configuration dialog:</p> <ul style="list-style-type: none"> <li>- select <b>Settings &gt; Device Assignment</b>,</li> <li>- select <b>Scan</b>,</li> <li>- select the Master device (with loaded and defined system channel),</li> <li>- therefore check the appropriate checkbox,</li> <li>- select <b>Apply</b>,</li> <li>- close the Master DTM configuration dialog via <b>OK</b>.</li> </ul>	<i>depends from device - (See help of the device manufacturer)</i>	-
13	For the Slave device with device assignment set driver settings and assign device	<ul style="list-style-type: none"> <li>- Double click to the device icon of the Slave.</li> <li>- The Slave DTM configuration dialog is displayed.</li> </ul> <p>In the Slave DTM configuration dialog:</p> <ul style="list-style-type: none"> <li>- select <b>Settings</b></li> <li>- Set the driver and assign the device.</li> </ul>	<i>depends from device - (See help of the device manufacturer)</i>	-
14	Configure Slave device	<p>Configure the Slave device.</p> <ul style="list-style-type: none"> <li>- Double click to the device icon of the Slave.</li> <li>- The Slave DTM configuration dialog is displayed.</li> </ul> <p>In the Slave DTM configuration dialog:</p> <ul style="list-style-type: none"> <li>- configure the Slave device</li> <li>- close the Slave DTM configuration dialog via <b>OK</b>.</li> </ul>	<i>depends from device - (See help of the device manufacturer)</i>	-
15	Configure Master device	<p>Configure the Master device.</p> <ul style="list-style-type: none"> <li>- Double click to the device icon of the Master.</li> <li>- The Master DTM configuration dialog is displayed.</li> </ul> <p>In the Master DTM configuration dialog:</p> <ul style="list-style-type: none"> <li>- configure the Master device</li> <li>- close the Master DTM configuration dialog via <b>OK</b>.</li> </ul>	<i>depends from device - (See help of the device manufacturer)</i>	-
16	Arrange Project	The project can be arranged in the network view by use of the mouse.	<i>Arrange Elements in the Network View</i>	45
17	Configure topology (if this option is available)	<p>Settings in the topology editor to make:</p> <ul style="list-style-type: none"> <li>- Connect the devices.</li> <li>- Configure the properties for devices and ports.</li> </ul>	<i>(See Operating Instruction Manual Toplogy Editor)</i>	-
18	Save project	<ul style="list-style-type: none"> <li>- select <b>File &gt; Save</b></li> <li>or</li> <li>- select <b>File &gt; Save As</b></li> </ul>	<i>(See Operating Instruction Manual of the Frame Application)</i>	-
19	Connect Master device	<ul style="list-style-type: none"> <li>- Right click to the device icon of the Master,</li> <li>- select context menu entry <b>Device &gt; Connect</b>.</li> </ul>	<i>Connect/disconnect Device</i>	48
20	Download Configuration	<ul style="list-style-type: none"> <li>- Right click to the device icon of the Master,</li> <li>- select context menu <b>Device &gt; Download</b>.</li> <li>- <i>Adhere to the safety information applying for this command.</i></li> </ul>	<i>Download to Device</i>	49



#	Step	Short Description	For detailed information see section	Page
21	Diagnosis	<ul style="list-style-type: none"><li>- Right click to the device icon of the Master,</li><li>- select context menu <b>Diagnosis</b>.</li><li>- The Master DTM diagnosis dialog is displayed.</li><li>- Continue with further device diagnosis,</li><li>- close the Master DTM diagnosis dialog via <b>OK</b>.</li></ul>	<i>depends from device - (See help of the device manufacturer)</i>	-
22	Disconnect	<ul style="list-style-type: none"><li>- Right click to the device icon of the Master,</li><li>- select <b>Device &gt; Disconnect</b>.</li></ul>	<i>Connect/disconnect Device</i>	48

Table 9: Getting Started - Configuration Steps

## 5.2 Safety Messages on Firmware or Configuration Download

If you perform a firmware download or a configuration download via the Master DTM or the Slave DTM (stand alone Slave at the root bus line) adhere to the necessary safety precautions to prevent personnel injury and property damage that may occur in consequence of a communication stop or in consequence of a mismatching system configuration. Also invalid or non-authorized firmware can damage your device.

### Personnel Injury

---



#### **Communication Stop**

- Together with the firmware download, an automated device reset is performed that will interrupt all network communications and established connections will drop.
- If you attempt to download the configuration during bus operation, the communication between Master and Slaves is stopped.
- Unexpected equipment operation may cause personal injury.
- Stop the application program before starting upgrading the firmware or downloading the configuration.
- Make sure that your equipment operates under conditions that prevent personal injury. All network devices should be placed in a fail-safe mode before upgrading the firmware or downloading a configuration.

#### **Mismatching System Configuration**

- Mismatching system configuration loaded into the device could result in faulty data mapping in the application program and thus unexpected equipment operation may cause personal injury.

---

*For more refere to next page.*

---

**Property Damage**

---

**NOTICE****Communication Stop**

- Together with the firmware download, an automated device reset is performed that will interrupt all network communications and established connections will drop.
- If you attempt to download the configuration during bus operation, the communication between Master and Slaves is stopped.

**Damage of Equipment**

- Unexpected equipment operation may cause property damage.
- Stop the application program before starting upgrading the firmware or downloading the configuration.
- Make sure that your equipment operates under conditions that prevent property damage . All network devices should be placed in a fail-safe mode before upgrading the firmware or downloading a configuration.

**Loss of Device Parameters**

- Both the firmware download and the configuration download erase the configuration data base and overwrites the existing firmware in the device.
- Device parameters that have not been saved non-volatile such as a temporary IP address are getting lost during the reset.
- Before you initiate firmware or a configuration download make sure that your project configuration data are saved non-volatile in order to prevent loss of configuration data.
- To complete the update and to make the device operable again, please re-download the configuration when this operation has finished.

**Invalid or non-authorized Firmware**

- Loading invalid or non authorized firmware files could render your module unusable. Only proceed with a authorized firmware update.

**Mismatching System Configuration**

- Mismatching system configuration loaded into the device could result in faulty data mapping in the application program and thus unexpected equipment operation may cause property damage.
-

## 5.3 The Device Catalog

The device catalog lists all devices, for which a DTM is installed on the used PC. A DTM represents one or more devices.

Before the devices can be used in the configuration, the DTM installed on this PC needs to be loaded in the device catalog. This is done automatically during the first start of the configuration software.

### 5.3.1 Load Device Catalog

Via the menu **Network > Device Catalog** the device catalog is opened and information like name of the device and manufacturer for the individual DTM is displayed.

If a new DTM is installed, the device catalog has to be reloaded, to use the new devices for the configuration. Further information about reloading the device catalog you find in section *Reload Device Catalog* on page 36.

If the **Device Catalog** is loaded, the installed devices are displayed in the device catalog depiction of the **netDevice** window.

The devices can be inserted in the project via drag and drop from the device catalog depiction in the **netDevice** window.

A detailed description about the device catalog depiction in the netDevice window you find in section *netDevice - Device Catalog* on page 18.

### 5.3.2 Reload Device Catalog

If new DTM are installed on the PC or device descriptions are imported, the device catalog must be reloaded to use the new devices in the configuration.

Via the menu **Network > Device Catalog** the device catalog opens and selecting the **Reload** button, it is searched for installed DTM on the PC.



---

**Note:** In order to reload the device catalog the, the current user must have **administrative rights**. Otherwise the **Reload** button is grayed out and the device catalog cannot be loaded.

---

The DTM are started and some information like device name, bus system, manufacturer and device type are read in when loading the device catalog. With this information the configuration software creates the device catalog.

The tree structure shows the current installed devices. Now the devices can be inserted in the project and configured there.

### 5.3.3 Devices of other Vendors

In order to select the desired device in the device catalog, note the details about the DTM and the device at the bottom of the window. When sorting by *Fieldbus* multiple devices with identical names by different vendors can be displayed.

The following figure shows the device catalog sorted by *Vendor*.

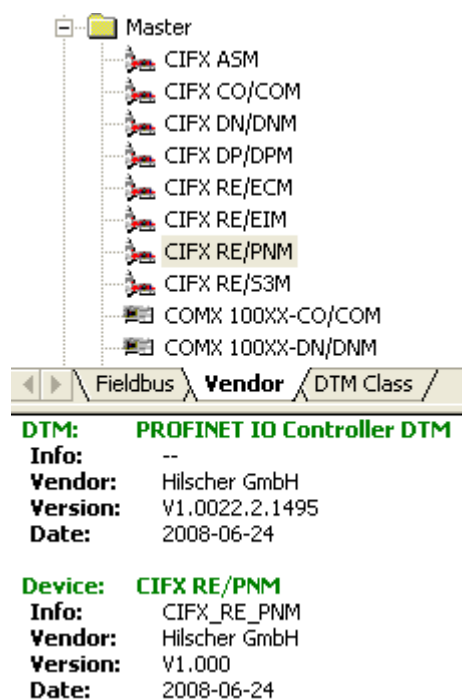


Figure 20: Device Catalog – Sorted by Vendor (Example)

The following figure shows the device catalog sorted by *Fieldbus*.

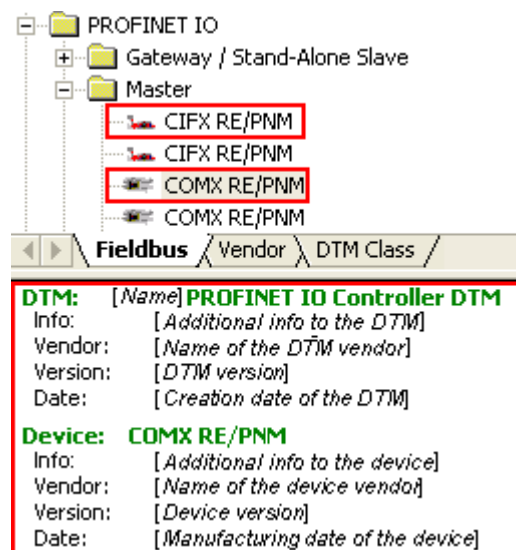


Figure 21: Device Catalog – Sorted by Fieldbus (Example)

For this sorting additional DTMs of other vendors can be displayed.

## 5.4 Installing Slave DTM or adding Device Description

In order to insert further Slave devices to the device catalog:

1. First check, if the Slave manufacturer provides a DTM.
2. Install this DTM.

Alternatively or if no DTM for the Slave is available use the device description file of the device specified by the manufacturer.

Bus System		File Type	File Extension
Real-Time Ethernet	EtherCAT	DDF	*.xml
	EtherNet/IP	EDS	*.eds
	PROFINET	GSDML	*.xml
	Sercos	SDDML	*.xml
Fieldbus	AS-Interface	EDS	*.eds
	PROFIBUS DP	GS, GSD, GSE, GSF	*.gs, *.gsd, *.gse, *.gsf
	CANopen	EDS	*.eds
	DeviceNet	EDS	*.eds

Table 10: Device Description File Types by System

1. Select **Network > Import Device Descriptions ....**

➤ The file selection dialog **Import Device Description** opens.

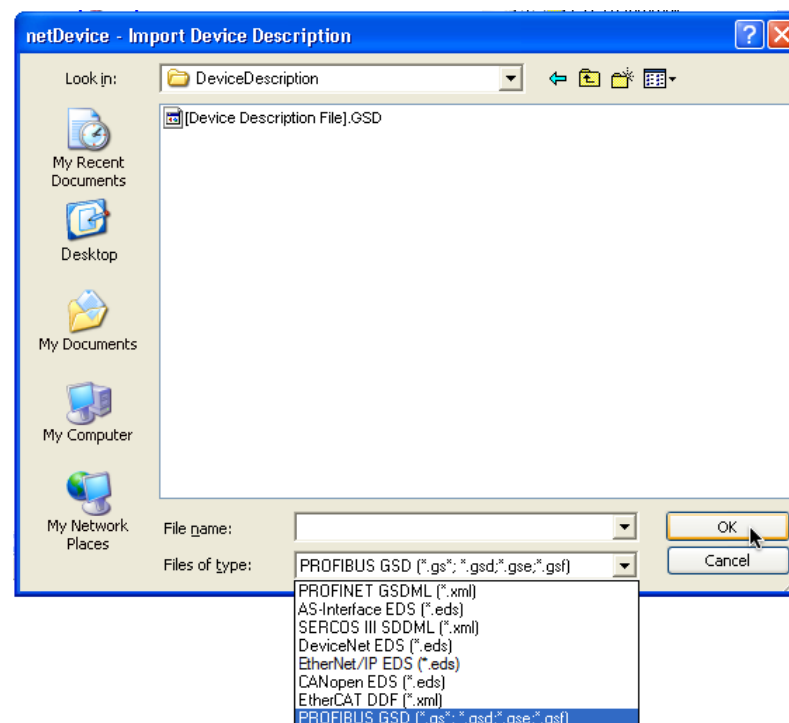


Figure 22: netDevice – Import Device Description

2. Select in the **File of type** list the bus system for which you intend to import device description files.
3. Select the path for the device description file.
4. Possibly select the path for the device icon.
5. Reload the device catalog (see section *Reload Device Catalog* on page 36).

## 5.5 PROFINET IO Device Instance

For PROFINET IO ‚Stand-Alone Slave‘ (Device) and ‚Slave‘ (Generic Device) in the device catalog all device instances of *one* device description file appear as separate devices. To distinguish the device instances originating from the same device description file, the device name is followed by the *firmware version* or the *range of the firmware versions* the device instance is valid for, as shown in the following figure.

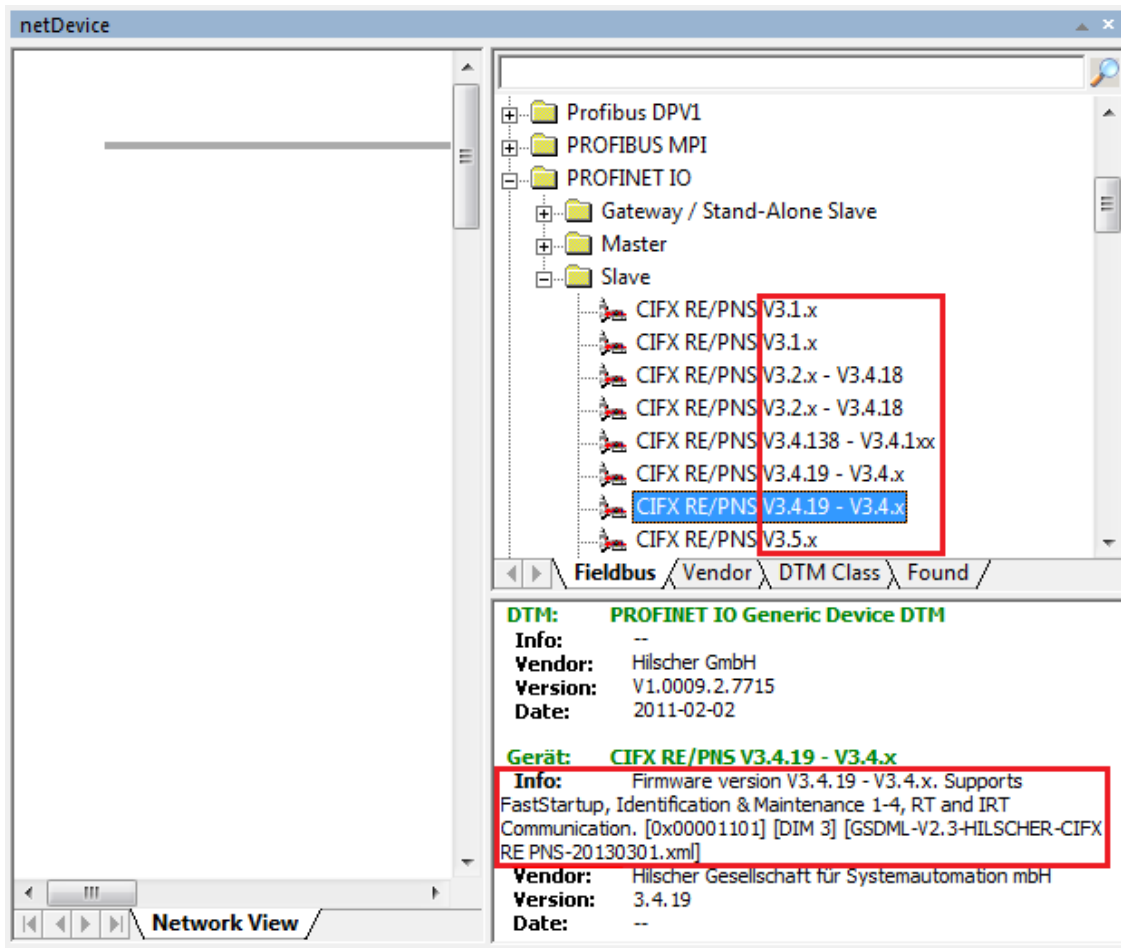


Figure 23: PROFINET IO Device Instance (Example Stand-Alone Slave)

Under **Device** > **Info** additional information is given about the selected device instance, such as the *firmware version*, the *feature set* or the *name of the device description file*.



**Note:** If a device instance appears in the device catalog twice with the same range for the firmware version, you can check under **Info** on which state of the device description file the device instance is referenced.

## 5.6 Insert Device in Project

Devices from the device catalog are added by drag and drop in the configuration area. With this action a DTM-Instance will be created.



### Important!

- Only devices with the same Fieldbus or Real-time Ethernet system can be connected to the same network.
- In order to select the desired device in the device catalog, note the details about the DTM and the device at the bottom of the window. When sorting by Fieldbus multiple devices with identical names by different vendors can be displayed.

### • Insert Master

To insert a **Master** device in a project, the Master has to be selected in the depiction of the device catalog in the netDevice window. Via drag and drop the device is inserted in the project.

The device can be inserted in both windows, in the network view of the **netDevice** and in the project tree of the **netProject**. These two windows are synchronized; the device is displayed in both windows.

It is possible to have more than one network in a project and therefore more than one Master.

### Please note:

In the **netDevice** window the **Master** device has to be inserted on the Root busline (green line). Each inserted communication channel of the Master is displayed at least by one fixed out-bound busline.

In the **netProject** window the **Master** needs to be inserted on the project folder directly.

### • Insert Slave



**Note:** A Slave or Gateway device can be connected to a bus, if it supports the same bus system.

To insert a **Slave** device in a project, the device has to be selected in the depiction of the device catalog in the netDevice window. The device is inserted into the project via drag and drop to the busline of the communication channel of the Master.

If in the netDevice device catalog view devices are displayed repeatedly under the same name, this devices can be differentiated via their revision or the date (see section *Notations to the DTM and to the Device* on page 20).

### Please note:

In the **netProject** window the **Slave** device must be inserted on the master icon directly.



**Note:** The **Master busline** or the **busline between the Master busline and the Slave device symbol** are always displayed in the same *fieldbus* or *protocol specific* color.



## 5.7 Cutting, copying, pasting Slave Devices

In the **netDevice** network view Slave devices in a project including all of its configuration settings can be cut or copied and then be pasted.

This way the project configuration can be enlarged by Slave devices the device configuration of which is identical or similar to that of Slave devices already existing in the project.

Via the context menu > **Cut**, **Copy** and **Paste** Slave devices in one or more networks can be cut or copied and pasted at a Master bus line. To allow pasting, the Master must support the fieldbus protocols of all Slaves. If, for example DPV0-PROFIBUS Slaves and PROFIBUS DPV1 Slaves have been copied, they can be pasted only to a Master which supports DPV0 and DPV1.

By this way the configuration needs to be made only once. The newly added Slave devices do not need to be parameterized and configured once more.



---

**Important:** Only devices of the same fieldbus or Real-time Ethernet system can be connected in a network.

---



---

**Note:** If Slave devices are added in a network via the context menu **Cut**, **Copy** and **Paste**, respectively the user needs to reset the device or station address for these devices in the Master configuration dialog.

---

### 5.7.1 Enlarging Project Configuration

To enlarge the project configuration via **Cut**, **Copy** or **Paste**, proceed as follows:

1. In the netDevice network view in one or more networks select the Slave devices to be added (see also section *Multiselection* on page 46).
2. Cut or copy the Slave devices via context menu **Cut** or **Copy**.
3. Via the context menu **Paste** paste these Slave devices at the Master bus line in the same or another network.
4. In the Master DTM configuration dialog adapt the device or station address of these Slave devices, device dependent also via the Master DTM context menu **Additional Functions**.

## 5.8 Delete Device from Project

To remove a device from the project configuration:

- First select the device by a mouse click.
- Then press the **Del** button on the keyboard.
- Or select **Delete** in the context menu of the device.
- ⇒ A security question appears, if the device really shall be deleted.



Figure 24: Security Question Delete Device



---

**Note:** If a device is deleted, all settings for this device get lost.

---

- Answer to the request by **Yes**.
- ⇒ The device is removed from the project configuration.

If a communication channel should be deleted that has connected Slaves, another security question appears:



Figure 25: Security Question Delete entire Network



---

**Note:** If a device is deleted, which has additional devices assigned to; the entire network is also deleted. This might include Gateways with Sub networks.

---

- Answer to the request by **Yes**.
- ⇒ The device is removed from the project configuration.

## 5.9 Working with Buslines

### 5.9.1 Description of the Buslines

Significance of the colors for the bus lines:

- **Root-bus line:** The **gray** bus line is the root bus line. All Masters are connected to this line.
- **Master Busline or Branch Line of the Slave device:** These bus lines are always in the respective *specific fieldbus or protocol* color.










Colors of the Bus Line		Meaning
	gray	Root Bus line
	yellow (dark)	fieldbus specific for AS-Interface Master
	magenta	fieldbus specific for PROFIBUS Master
	dark green	fieldbus specific for CANopen Master
	orange yellow	fieldbus specific for DeviceNet Master
	bottle green	protocol specific for PROFINET IO Controller
	darkgold	protocol specific for EtherNet/IP Scanner
	yellow	protocol specific for EtherCAT Master
	red	protocol specific for Sercos Master

Table 11: Colors of the Bus Lines

## 5.9.2 Add / Remove Busline

In the network view in the netDevice window the project can be arranged and edited graphically. That means, buslines can be added and removed.



**Note:** The changes add / remove busline in the network view have no effect to the real hardware configuration.

### • Add Busline

To add a busline:

- Select the busline.
- Select **Network > Add Busline**.

Or

- Select  in the toolbar.

Or

- Right click on the busline and select **Add Busline**.




- A busline is added on the active bus. If more than one bus is selected, the busline is added only at the first selected bus.

### • Delete Last Busline

To remove a busline:

- Select a busline.
- Select **Network > Delete Last Busline**.

Or

- Select  in the toolbar.

Or

- Right click on the busline and select **Delete Last Busline**.



- The lastly added busline of this bus is removed. If more than one bus is selected, only the busline of the first bus is deleted.

### 5.9.3 Arrange Elements in the Network View

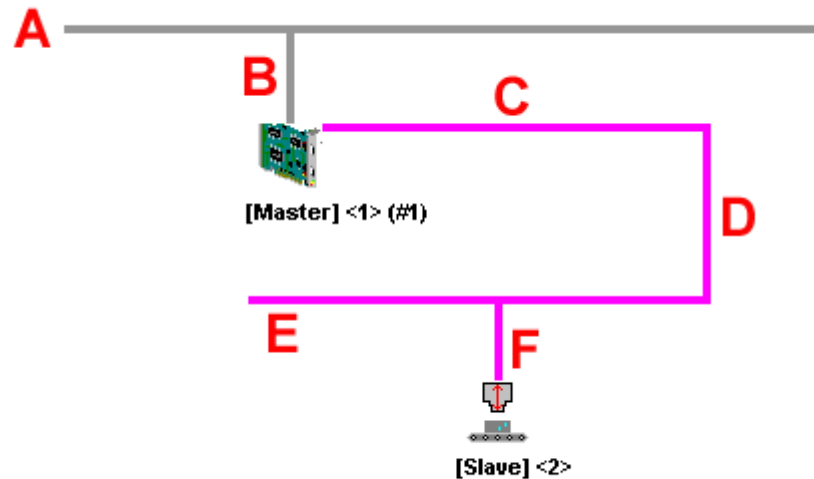


Figure 26: Buslines

Buslines and device icons can be selected and moved to arrange them in the graphical configuration.

To move a busline or an icon it is necessary to select it by clicking on it. A selected busline or device is displayed with a blue colored frame around the icon.

- **Move Device Icon**

Each device icon in the project can be moved by clicking and holding the left mouse button. The fixed buslines move with the icons and the built configuration persists.

Another possibility to move the selected device icons consists in using the cursor keys. If the SHIFT key is pressed, the icons are moved faster.

- **Move Buslines**

Busline **A** is the **Root Busline** and it can be positioned by holding the mouse button.

Busline **B** is the **Branch Line of the Master device** and can not be moved. If the Master Icon is moved, the busline moves with this icon automatically.

Busline **C** is the **basic line of the Fieldbus or the Real-time Ethernet system** (Master bus line) inherently. It also can not be moved singly, but it is moved with the device icons automatically.

Busline **D** and **E** are **variable added buslines** (part of the Master bus line) of the Fieldbus. They can be selected and moved or resized.

Busline **F** is the **branch line of the Slave device** (bus line between the Master bus line and the Slave device icon). It is the connection line from the Slave to the bus. This line is moved automatically (like busline B) with the device icon. This line can not be moved independently.

## 5.9.4 Multiselection

Multiselection makes it possible to select more than one device and/or busline. This is helpful if more than one element should be arranged at the same time. Two possibilities are available for multiselection:

- **Only with the Mouse**

- Click in the configuration window.
- Hold the mouse button and draw a frame around the elements you want to select.

- **With Mouse and the SHIFT Key**

- Select the first element with a left mouse click (busline or device icon).
- Hold the SHIFT key on the keyboard and click on the next elements you want to select.



---

**Note:** Only buslines, which can be changed manually, can be selected. Descriptions of the single buslines you find in section *Arrange Elements in the Network View* on page 45.

---

## 6 Configuration

### 6.1 Online/Offline Configuration

The configuration of a device is done in the DTM configuration dialog of the device.

This one can be opened via double click to the device in the netDevice network view, via the context menu **Configuration** or via **Device > Configuration**.

A distinction is made between offline configuration and online configuration:

- **Offline Configuration**

If a device is parameterized **offline** in the application, the configuration has to be loaded into the device via the download to transfer the parameter data into the device.

When a configuration already exists in the device, this configuration is overwritten by the download of the new parameter.

- **Online Configuration**

Requirement for the **online** configuration is that the hardware is installed and can be activated by the communication DTM.

In case of **online** configuration, the parameter data set in the application is transferred into the device automatically without a download. If the device contains parameter data and supports the online Configuration, the stored parameter data is transferred to the application without an upload from the device.



**Note:** It is manufacturer specific, if the used device supports an online Configuration. For further information about the used device please ask the hardware manufacturer or see the help file of the device when device dialog is open.



**Note:** Upload and Download are not available for each device. If a device supports these functions is manufacturer specific. For further information about the used device please ask the hardware manufacturer or see the help file of the device when device dialog is open.

More information about the Download you find in section *Download to Device* on page 49. More information about the Upload you find in section *Upload from Device* on page 49.

## 6.2 Connect/disconnect Device



---

**Note:** Several DTM functions require an online connection from the DTM to the device, e. g. **Diagnosis** or the configuration download in the FDT Framework.

More information about the Download you find in section *Download to Device* on page 49. More information about the Upload you find in section *Upload from Device* on page 49.

---

A device can be connected by marking the device in the netDevice network view and by selecting the menu **Device > Connect** or via the context menu of the device and **Connect**.

If a Master is selected and then **Connect**, only the Master device is connected. If **Connect** is selected in case of a marked Slave device, the device is connected via the parent communication channel. That means the Master is connected, too.

Now the device is online. This is displayed by a green background of the device description.

If the device should be disconnected from the bus, the menu **Device > Disconnect** or the context menu of the device has to be selected and **Disconnect**. In case of a Master the Slaves of this network will be disconnected, too.

That means the Master is connected to the bus automatically, if a Slave is connected; and the Slaves are automatically disconnected, if the Master is disconnected.



---

For more information on how to connect or disconnect a DTM to the device, refer to the device specific help.

---



## 6.2.1 Download to Device



---

**Note:** It is manufacturer depending if the device supports the **Download** function. Look up in the manufacturer specific manual for further information.

---

If a device is parameterized *offline* in the DTM (application program), a download to the device has to be made to transfer the configuration with the parameter data to the device.

The download is made via the menu **Device > Download** or via the context menu of the device and then **Download**.

Now the current configuration in the application program is loaded down into the device.

### netDevice Message: Download

If the download is started as long as the Slave devices are connected to the Master device, the following message is displayed: **If you attempt to download during bus operation, communication between master and Slaves is stopped. Do you really want to download?**



---

**Important:** If the communication between the Master and the Slave devices is stopped, the data exchange between the Master device and the Slave devices is stopped.

---

- Click to **Yes**, if you intend to download the configuration, otherwise click to **No**.

*Adhere to the safety information applying for this command.*

## 6.2.2 Upload from Device



---

**Note:** It is manufacturer depending if the device supports the **Upload** function. Look up in the manufacturer specific manual for further information.

---

If a device contains parameter data and this parameter data should be loaded into the DTM (application program), an upload from the device has to be made.

Then you have to select the menu **Device > Upload** to make an Upload from the device. The current configuration in the device is loaded into the application program.

## 7 Appendix

### 7.1 User Rights

Apart from the administrator, which has full rights of access, there are four further user levels, which have different rights of access in each case for parameterization and configuration:

Action	Observer	Operator	Maintenance	Planning Engineer
<b>Menu Device and Context Menu</b>				
Connect	Yes	Yes	Yes	Yes
Disconnect	Yes	Yes	Yes	Yes
Upload	No	Yes	Yes	Yes
Download	No	No	Yes	Yes
Cut	No	No	Yes	Yes
Copy	No	No	Yes	Yes
Paste	No	No	Yes	Yes
Configuration	Yes	Yes	Yes	Yes
Measured Value	Yes	Yes	Yes	Yes
Simulation	Yes	Yes	Yes	Yes
Diagnosis	Yes	Yes	Yes	Yes
<b>Menu Network</b>				
Add Busline	No	No	Yes	Yes
Remove last Busline	No	No	Yes	Yes
Start Project Debug Mode	Yes	Yes	Yes	Yes
Stop Project Debug Mode	Yes	Yes	Yes	Yes
Device Catalog	Yes	Yes	Yes	Yes
Import Device Descriptions ...	No	No	Yes	Yes
Print Project Data	Yes	Yes	Yes	Yes

Table 12: User Levels

## 7.2 List of Figures

Figure 1: netDevice - Network View and Device Catalog (Principle)	14
Figure 2: Example for netDevice - Network View and Device Catalog	14
Figure 3: netDevice and netProject - Network View (Principle)	15
Figure 4: Example for netDevice and netProject - Network View	16
Figure 5: Notation of the Device Description	16
Figure 6: netDevice - Device Catalog (Principle)	18
Figure 7: Example for netDevice - Network View and Device Catalog	18
Figure 8: Search Function in the Device Catalog	19
Figure 9: Search Function in the Device Catalog – Search Result	19
Figure 10: netDevice - Device Catalog - Notations to the DTM and to the Device (Principle)	20
Figure 11: Example for netDevice - Device Catalog	20
Figure 12: netProject (Principle) (left side), Example (right side)	21
Figure 13: Menu Device (left), Example Context Menu for Master or Slave (right)	23
Figure 14: Change Symbolic Name	28
Figure 15: Notation of the Device Description	28
Figure 16: Menu Network	29
Figure 17: netDevice Toolbar Network	30
Figure 18: netDevice Debug Toolbar - Start Project Debug Mode	30
Figure 19: netDevice Debug Toolbar - Stop Project Debug Mode	30
Figure 20: Device Catalog – Sorted by Vendor (Example)	37
Figure 21: Device Catalog – Sorted by Fieldbus (Example)	37
Figure 22: netDevice – Import Device Description	38
Figure 23: PROFINET IO Device Instance (Example Stand-Alone Slave)	39
Figure 24: Security Question Delete Device	42
Figure 25: Security Question Delete entire Network	42
Figure 26: Buslines	45

## 7.3 List of Tables

Table 1: Overview	4
Table 2: Signal Words in Safety Messages on Personal Injury	13
Table 3: Signal Words in Safety Messages on Property Damage	13
Table 4: Notation of the Device Description	16
Table 5: Menu Device and Context Menu	22
Table 6: Menu Device	24
Table 7: Additional Functions	27
Table 8: Menu Network	29
Table 9: Getting Started - Configuration Steps	33
Table 10: Device Description File Types by System	38
Table 11: Colors of the Bus Lines	43
Table 12: User Levels	50

## 7.4 Glossary

### Master

Master devices determine the data traffic on the bus. A master may send messages without external request, if it is in the possession of the token (bus access authorization).

### Slave

Slave devices are peripheral devices, like for example I/O devices or drives. Slave devices are also called passive participants. They do not receive the bus access authorization. That means, they may only accept received messages from the Master or send a message to the Master after enquiry of the Master.

### Device Instance

According to the version of the PROFINET IO Slave device firmware the device instance specifies, which features the device has. The device instance is a module of the GSDML to describe the device parameters device specific.

In **netDevice** for PROFINET IO in the device catalog under 'Stand-Alone-Slave' or 'Slave' all device instances that derive from the same device description file, appear as separate devices.

### DTM

Device Type Manager.

The Device Type Manager (DTM) is a software module with graphical user interface for the configuration or for diagnosis of device.

### FDT

Field Device Tool

FDT specifies an interface, in order to be able to use DTM (Device Type Manager) in different applications of different manufacturers.

## 7.5 Contacts

### Headquarters

#### Germany

Hilscher Gesellschaft für  
Systemautomation mbH  
Rheinstrasse 15  
65795 Hattersheim  
Phone: +49 (0) 6190 9907-0  
Fax: +49 (0) 6190 9907-50  
E-Mail: [info@hilscher.com](mailto:info@hilscher.com)

#### Support

Phone: +49 (0) 6190 9907-99  
E-Mail: [de.support@hilscher.com](mailto:de.support@hilscher.com)

### Subsidiaries

#### China

Hilscher Systemautomation (Shanghai) Co. Ltd.  
200010 Shanghai  
Phone: +86 (0) 21-6355-5161  
E-Mail: [info@hilscher.cn](mailto:info@hilscher.cn)

#### Support

Phone: +86 (0) 21-6355-5161  
E-Mail: [cn.support@hilscher.com](mailto:cn.support@hilscher.com)

#### France

Hilscher France S.a.r.l.  
69500 Bron  
Phone: +33 (0) 4 72 37 98 40  
E-Mail: [info@hilscher.fr](mailto:info@hilscher.fr)

#### Support

Phone: +33 (0) 4 72 37 98 40  
E-Mail: [fr.support@hilscher.com](mailto:fr.support@hilscher.com)

#### India

Hilscher India Pvt. Ltd.  
Pune, Delhi, Mumbai  
Phone: +91 8888 750 777  
E-Mail: [info@hilscher.in](mailto:info@hilscher.in)

#### Italy

Hilscher Italia S.r.l.  
20090 Vimodrone (MI)  
Phone: +39 02 25007068  
E-Mail: [info@hilscher.it](mailto:info@hilscher.it)

#### Support

Phone: +39 02 25007068  
E-Mail: [it.support@hilscher.com](mailto:it.support@hilscher.com)

#### Japan

Hilscher Japan KK  
Tokyo, 160-0022  
Phone: +81 (0) 3-5362-0521  
E-Mail: [info@hilscher.jp](mailto:info@hilscher.jp)

#### Support

Phone: +81 (0) 3-5362-0521  
E-Mail: [jp.support@hilscher.com](mailto:jp.support@hilscher.com)

#### Korea

Hilscher Korea Inc.  
Seongnam, Gyeonggi, 463-400  
Phone: +82 (0) 31-789-3715  
E-Mail: [info@hilscher.kr](mailto:info@hilscher.kr)

#### Switzerland

Hilscher Swiss GmbH  
4500 Solothurn  
Phone: +41 (0) 32 623 6633  
E-Mail: [info@hilscher.ch](mailto:info@hilscher.ch)

#### Support

Phone: +49 (0) 6190 9907-99  
E-Mail: [ch.support@hilscher.com](mailto:ch.support@hilscher.com)

#### USA

Hilscher North America, Inc.  
Lisle, IL 60532  
Phone: +1 630-505-5301  
E-Mail: [info@hilscher.us](mailto:info@hilscher.us)

#### Support

Phone: +1 630-505-5301  
E-Mail: [us.support@hilscher.com](mailto:us.support@hilscher.com)